

Integer Factorisation on the AP1000*

Craig Eldershaw
Mathematics Department
University of Queensland
St Lucia, Queensland 4072
cs324391@student.uq.edu.au

Richard P. Brent
Computer Sciences Laboratory
Australian National University
Canberra, ACT 0200
rpb@cslab.anu.edu.au

Abstract

We compare implementations of two integer factorisation algorithms, the elliptic curve method (ECM) and a variant of the Pollard “rho” method, on three machines (the Fujitsu AP1000, VP2200 and VPP500) with parallel and/or vector architectures. ECM is scalable and well suited for both vector and parallel architectures.

1 Introduction

The factorisation of large integers is a significant mathematical problem with practical applications to public-key cryptography [21]. Although the theoretical complexity of factorisation is unknown, it is a computationally expensive task with the best known algorithms. The development of new algorithms and faster machines has made the factorisation of “general” integers with 100–120 digits feasible.

Several authors have considered vector and parallel implementations of the MPQS and NFS algorithms [5, 8, 12, 16, 19, 20]. These algorithms have the property that the run-time depends mainly on the size of the number N to be factored. For another class of algorithms the run-time depends mainly on the size of the factor found. This class includes Lenstra’s “elliptic curve method” (ECM) [14] and Pollard’s “rho” method [18], which are considered in this paper.

We have implemented variants of ECM and Pollard “rho” on three computers with different architectures –

- The Fujitsu AP1000, a parallel machine with up to 1024 processors [10]. Each processor is a 25MHz RISC microprocessor with 16MB of memory. The processors are connected by a torus with wormhole routing. Each processor has a floating-point unit with a peak speed of 5.6 Mflop in double-precision. Our machine has 128 processors, so its peak speed is about 0.7 Gflop.
- The Fujitsu VP2200/10, a vector processor with a peak speed of 1.25 Gflop [22].

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- The Fujitsu VPP500, a parallel machine with up to 224 vector processors connected by a crossbar network [6]. Each processor is similar to the VP2200/10 and has a peak speed of 1.6 Gflop. The machine available to us had 4 processors and peak speed 6.4 Gflop.

In the following Sections we describe the implementation of ECM and Pollard “rho” on the AP1000, VP2200 and VPP500, and compare their performance. Many examples of successful factorisations may be found in [4, 5, 7], so here we concentrate on vectorisation and parallelisation aspects of the implementations.

2 The Elliptic Curve Method

The elliptic curve method (usually abbreviated ECM) was proposed by Lenstra [14]. Practical improvements, such as the addition of a second phase, were suggested by Brent [3], Montgomery [15] and others. Each “trial” of the algorithm depends on a random seed and has a positive (but generally small) probability of finding a factor f . Because many independent trials can be performed in parallel, ECM is obviously amenable to a parallel implementation. The speedup is expected to be proportional to the number of processors provided f is not too small.

A vectorised implementation of ECM on the Fujitsu VP100 was written in 1988. The language used was a dialect of Fortran (close to Fortran 77 with directives for vectorisation). An improved version was implemented in 1991 on the Fujitsu VP2200. Because the Fujitsu vector processors are designed for fast floating-point arithmetic, the inner loop uses 64-bit floating-point multiply, add, INT and DFLOAT operations (for details see [5]). The base $\beta = 2^{26}$ of the multiple-precision number representation is chosen so that integers up to β^2 can be represented exactly in floating-point format. Operations which are not critical to performance, such as input and output, are done with the MP package [1], which is convenient but slow because it was not written with vectorisation in mind.

In 1994 Eldershaw modified Brent’s VP2200 implementation of ECM to obtain AP1000 and VPP500 implementations. The modifications were along the lines suggested in [4]. On the AP1000 each processor performs one or more independent trials (without vectorisation) and reports back to the host processor if a factor is found. On the VPP500 it is important for each processor to perform several trials, since the vector length of inner-loop operations is proportional to the number of trials per processor.

In more detail: P blocks of R trials (phase 1) are carried out simultaneously on P processors. The trials within each block have consecutive seed values, and the first seed value for each block is R larger than that for the previous block. In effect $R \times P$ trials are being carried out with consecutive seeds. At the end of the block of R trials (phase 1), each processor checks if a factor has been found. If not, each processor carries out phase 2 of the algorithm for each of its R trials using the corresponding first phase results.

In [4, 5] Brent gave the theoretical expected run-time T_P for a machine with P processors:

$$T_P = T_1/P + O(T_1^{1/2+\epsilon}) \quad (1)$$

Tests were run on the AP1000 with varying numbers of processors (powers of 2 from 2^0 to 2^7). The results confirmed (1). Typical results are shown in Figure 1. Linear regression shows that there is less than 3% error in the gradient of a linear fit to the data points. We

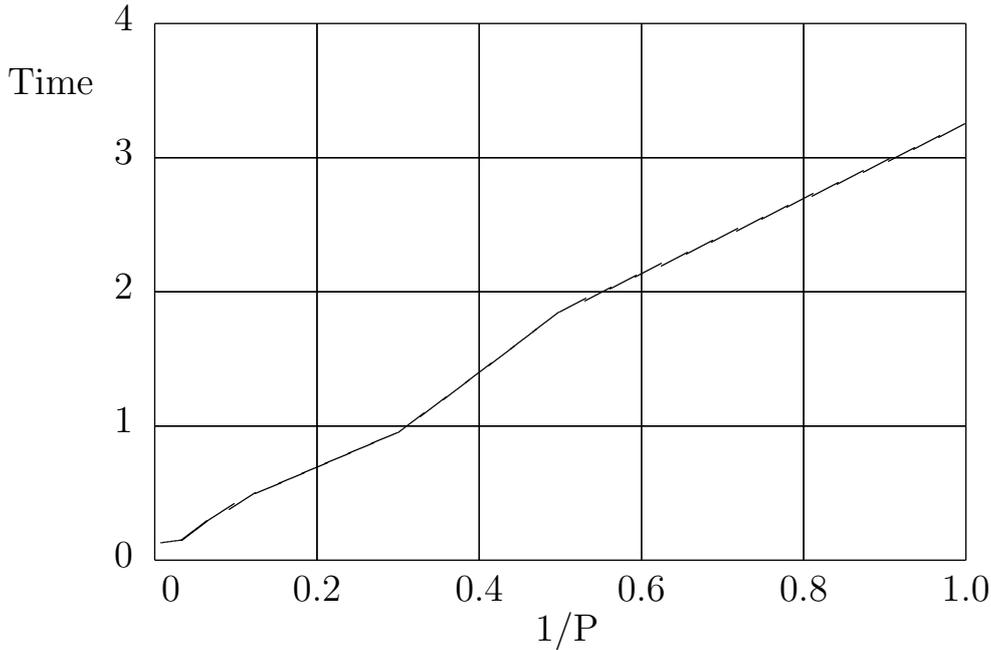


Figure 1: Time T_P (arbitrary units) versus $1/P$ for ECM on AP1000

can say that ECM is scalable, meaning that the speedup for sufficiently large problems on a parallel machine with P processors is proportional to P .

The VP2200 and VPP500 programs were very effectively vectorised – in a typical run, at least 90% of the overall time was spent using the vector unit. The AP1000 ran only in scalar mode, but the multiple processors reduced the time by two orders of magnitude (as predicted in (1)) in comparison to a single processor run.

To give a typical example of the performance of the programs: a test run found a 32-digit factor

12567880628356583361572166052961

of a 79-digit number ($98^{85} + 1$ divided by known factors) in 1555 seconds on the first attempt on the AP1000, using the first phase of ECM with limit 100000 and 256 trials. The same computation could be performed on the VP2200 in 915 seconds.

Another example: using ECM with limit 240000 and 256 trials, a 41-digit factor

25233450176615986500234063824208915571213

of a 92-digit number ($55^{126} + 1$ divided by known factors) was found by the second phase in 7042 seconds on the AP1000. (To find factors of this size by ECM requires an element of luck.)

The Fortran compilers on the VP2200 and VPP500 can achieve close to peak speed for well-vectorised loops. Considering their peak speeds, the VPP500 should have performed about 5 times faster than the VP2200. However, various overheads due to the parallelisation reduced this ratio for short runs. Times typical of small runs on the three machines are: on the VP2200, 30 seconds; on the AP1000, 68 seconds; and on the VPP500, 23 seconds (all to perform the same amount of work). However for longer runs, the VPP500 performed better. For example, on one run the VP2200 took 292 seconds and the VPP500

took only 50 seconds. The ratio (5.84) is greater than the ratio of peak speeds (5.12). This may be because the VPP500 has a better memory bandwidth per flop, so it is easier for the compiler to achieve close to peak performance in vectorised loops. If INT and DFLOAT are counted as floating-point operations (which is reasonable, since they use the vector pipelines) then our programs achieve greater than 55% of peak performance on the VP2200 and about 64% on the VPP500.

3 Brent-Pollard “rho”

The Brent-Pollard “rho” programs, written by Eldershaw, were based on algorithm P_2'' in Brent’s paper [2] which improved the efficiency of Pollard’s original “rho” method [18]. On the AP1000 the calculations are performed using MP [1]. Parallelisation is carried out as suggested in [4]. That is, each processor independently repeats the same procedure using a different function F (the difference depending upon a single parameter) to generate a pseudo-random sequence.

As pointed out in [4], a speedup of order \sqrt{P} is all that can be expected when using P processors. This gives an *expected* run time of:

$$T_P \sim T_1/\sqrt{P} \tag{2}$$

assuming that the computation stops as soon as one processor finds a factor.

Tests were run on the AP1000 with the number of processors varying in powers of two (from 2^0 to 2^7). The results were reasonably consistent with the prediction (2). Linear regression of T_P vs $1/\sqrt{P}$ shows an error of less than 10% in the gradient of a linear fit to the data points. Experimental data points along with the fitted line (dotted) are shown in Figure 2. Parallelisation of the “rho” algorithm is not nearly as effective as for the ECM, i.e. “rho” is not scalable.

Consider implementing the “rho” algorithm on a vector machine with vector lengths v . Because of vector startup times and parts of the code which run in scalar mode, we can expect the time for v independent function evaluations to be proportional to $v + v_{1/2}$, where $v_{1/2}$ is a constant. Since the expected number of function evaluations to find a factor is proportional to \sqrt{v} , the expected run time T_v is proportional to

$$\frac{v + v_{1/2}}{\sqrt{v}} \tag{3}$$

The function in (3) has a minimum of $2\sqrt{v_{1/2}}$ at $v = v_{1/2}$. Thus, the maximum speedup is approximately $\sqrt{v_{1/2}}/2$.

A vectorised version was implemented on the VP2200. The effect of varying the vector length v is shown in Figure 3. Note that the units of time are arbitrary and $T_1 = 19.4$ is well off the page. The results are roughly as predicted by (3). For the optimal value of v (a few hundred) the speedup over $v = 1$ is about 12.

4 Conclusion

The effect of parallelisation was as predicted – ECM obtains close to linear speedup, but “rho” only obtains a speedup of order \sqrt{P} on a machine with P processors. Nevertheless,

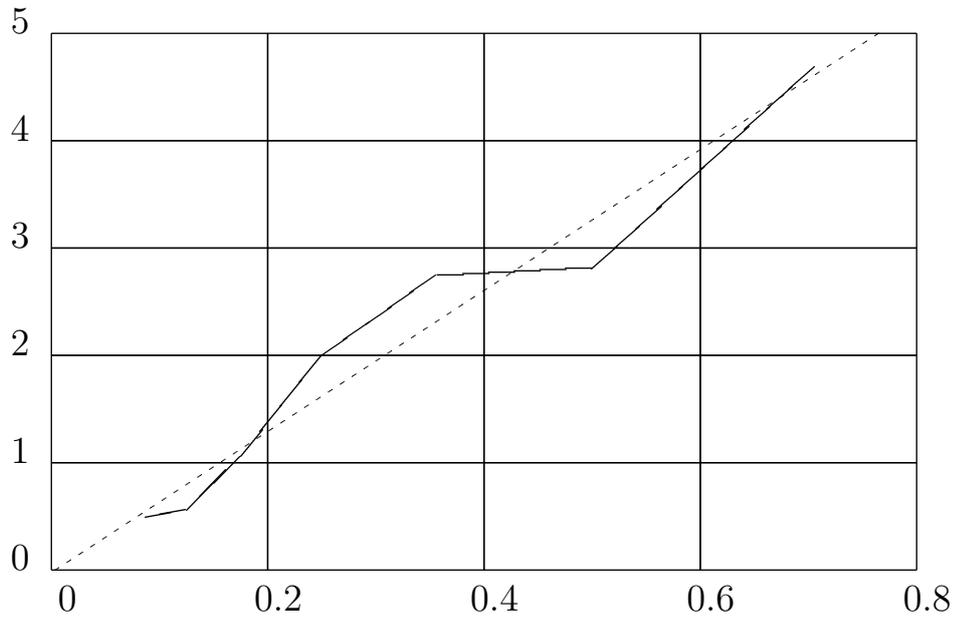


Figure 2: Time T_P (arbitrary units) versus $1/\sqrt{P}$ for Brent-Pollard Rho

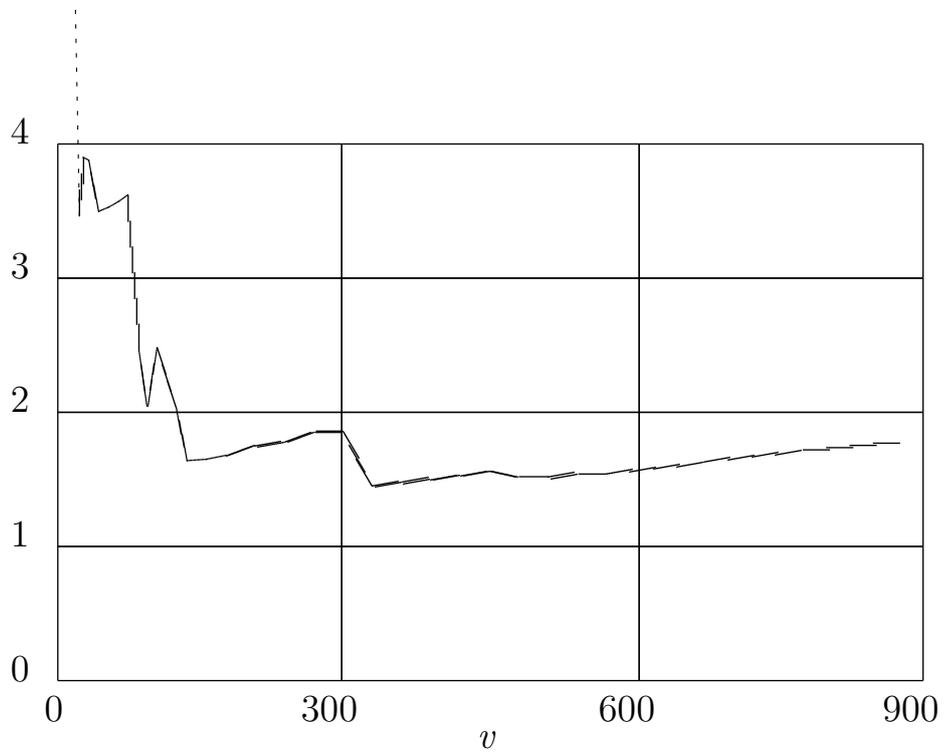


Figure 3: Time versus vector length v for Brent-Pollard Rho

“rho” is much simpler than ECM and should be faster than ECM for small factors and a small number of processors, provided both implementations are equally well vectorised.

Parallel versions of the MPQS and NFS methods have not yet been implemented on the AP1000 or VPP500. However, we would expect that a careful implementation of these methods would obtain good speedup. Most of the work involves sieving, and the sieving phase can be split across many processors and/or vectorised efficiently [12, 13, 20]. After sieving is completed a large sparse linear system has to be solved over a finite field. This is relatively easy. For example, the factorisation of a 105-digit number by GNFS, described in [16], required the solution of a linear system with 1.29 million columns with 30 nonzeros per column. It was solved using a block Lanczos algorithm [17] which could have been parallelised. Other parallel algorithms for the solution of large sparse linear systems are discussed in [11].

A good factorisation strategy is to use trial division to remove very small factors, possibly followed by Brent-Pollard “rho” and/or Pollard “ $p \pm 1$ ” [15], and then ECM. If ECM can not complete the factorisation in a reasonable time, MPQS (or NFS) is needed. Even in this case, the time spent on ECM is not wasted, because the time required by MPQS is greatly reduced for each factor found by ECM. Most of the nontrivial factorisations listed in [7] were found using a combination of methods, and could not have been found in a reasonable time with a single method.

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