A Multi-level Blocking Distinct-degree Factorization Algorithm

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ABSTRACT. We give a new algorithm for performing the distinct-degree factorization of a polynomial P(x) over $\mathrm{GF}(2)$, using a multi-level blocking strategy. The coarsest level of blocking replaces GCD computations by multiplications, as suggested by Pollard (1975), von zur Gathen and Shoup (1992), and others. The novelty of our approach is that a finer level of blocking replaces multiplications by squarings, which speeds up the computation in $\mathrm{GF}(2)[x]/P(x)$ of certain interval polynomials when P(x) is sparse.

As an application we give a fast algorithm to search for all irreducible trinomials $x^r + x^s + 1$ of degree r over GF(2), while producing a certificate that can be checked in less time than the full search. Naive algorithms cost $O(r^2)$ per trinomial, thus $O(r^3)$ to search over all trinomials of given degree r. Under a plausible assumption about the distribution of factors of trinomials, the new algorithm has complexity $O(r^2(\log r)^{3/2}(\log \log r)^{1/2})$ for the search over all trinomials of degree r. Our implementation achieves a speedup of greater than a factor of 560 over the naive algorithm in the case r = 24036583 (a Mersenne exponent).

Using our program, we have found two new primitive trinomials of degree 24036583 over GF(2) (the previous record degree was 6972593).

1. Introduction

The problem of factoring a univariate polynomial P(x) over a finite field F often arises in computational algebra [7, 11, 12]. An important case is when F has small characteristic and P(x) has high degree but is *sparse*, that is P(x) has only a small number of nonzero terms.

To simplify the exposition we restrict attention to the case where F = GF(2) and P(x) is a trinomial

$$P(x) = x^r + x^s + 1, r > s > 0,$$

although the ideas apply more generally and should be useful for factoring sparse polynomials over fields of small characteristic.

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Our aim is to give an algorithm with good amortized complexity, that is, one that works well on average. Since we are restricting attention to trinomials, we average over all trinomials of fixed degree r.

Our motivation is to speed up previous algorithms for searching for irreducible trinomials of high degree [5, 6, 13, 14]. For given degree r, we want to find all irreducible trinomials $x^r + x^s + 1$.

In our examples the degree r is a Mersenne exponent, i.e., $2^r - 1$ is a Mersenne prime. In this case an irreducible trinomial of degree r is necessarily primitive. In general, without the restriction to Mersenne exponents, we would need the prime factorisation of $2^r - 1$ in order to test primitivity (see e.g., [10]).

We are only interested in Mersenne exponents $r = \pm 1 \mod 8$, because in other cases Swan's theorem [15, 21, 22] rules out irreducible trinomials of degree r (except for s = 2 or r - 2, but these cases are usually easy to handle: for example if r = 13466917 or 20996011 we have $r = 1 \mod 3$, so $x^r + x^2 + 1$ is divisible by $x^2 + x + 1$).

Mersenne exponents can be found on the GIMPS website [23]. At the time of writing, the five largest known Mersenne exponents r satisfying the condition $r=\pm 1 \mod 8$ are r=6972593, 24036583, 25964951, 30402457 and 32582657. In the smallest case r=6972593, a primitive trinomial was found by Brent, Larvala and Zimmermann [6] using an efficient implementation of the naive algorithm. However, it was not feasible to consider the larger Mersenne exponents r using the same algorithm, since the time complexity of this algorithm is roughly of order r^3 , and the next case r=24036583 would take about 41 times longer than r=6972593. With the new "fast" algorithm described in this paper we have been able to find two primitive trinomials of degree r=24036583 in less time than the naive algorithm took for r=6972593. The speedup over the naive algorithm for r=24036583 is about a factor of 560.

If $x^r + x^s + 1$ is reducible then we want to provide an easily-checked *certificate* of reducibility. The certificate can simply be an encoding of an irreducible factor f of $x^r + x^s + 1$. We choose the factor f of smallest degree d > 0. In case there are several factors of equal smallest degree d, we give the one that is least in lexicographic order, e.g., $x^3 + x + 1$ is preferred to $x^3 + x^2 + 1$.

1.1. Distinct-degree factorization. Factorization of polynomials over finite fields typically proceeds in three stages: square-free factorization, distinct-degree factorization, and equal-degree factorization. The most time-consuming stage, and the one that we consider in this paper, is distinct-degree factorization [8, 10, 11].

The program described in §4.3 performs equal-degree factorization when it is necessary to split a product of equal-degree factors in order to give the unique certificate described above, but this is cheap (on average) because it is rarely required for factors of high degree.

In the complexity analysis we only consider the time required to find *one* non-trivial factor (it will be a factor of smallest degree) or output "irreducible", since that is what is required in the search for irreducible trinomials. However the algorithm outlined in §2.4 readily extends to a complete distinct-degree factorization.

1.2. Factorization over GF(2). It is well-known that $x^{2^d} + x$ is the product of all irreducible polynomials of degree dividing d. For example,

$$x^{2^3} + x = x(x+1)(x^3+x+1)(x^3+x^2+1).$$

Thus, a simple algorithm to find a factor of smallest degree of P(x) is to compute $GCD(x^{2^d} + x, P(x))$ for d = 1, 2, ... The first time that the GCD is nontrivial, it contains a factor of minimal degree d. If the GCD has degree > d, it must be a product of factors of degree d. If no factor has been found for $d \le r/2$, where $r = \deg(P(x))$, then P(x) must be irreducible.

Some simplifications are possible when $P(x) = x^r + x^s + 1$ is a trinomial over GF(2) with r or s odd (otherwise P(x) is trivially reducible):

- (1) We can skip the case d = 1 because a trinomial can not have a factor of degree 1.
- (2) Since $x^r P(1/x) = x^r + x^{r-s} + 1$, we only need consider $s \le r/2$.
- (3) We can assume that P(x) is square-free.
- (4) By applying Swan's theorem, we can often show that the trinomial under consideration has an odd number of irreducible factors; in this case we only need check $d \leq r/3$ before claiming that P(x) is irreducible.

2. Complexity of the algorithm

Note that x^{2^d} should not be computed explicitly; it is much better to compute x^{2^d} mod P(x) by repeated squaring. The complexity of squaring modulo a trinomial of degree r is only S(r) = O(r) bit-operations.

2.1. Complexity of polynomial multiplication and squaring. We need to perform multiplications in GF(2)[x]/P(x), and an important special case is squaring a polynomial modulo P(x), so we consider the bit-complexity of these operations.

Multiplication of polynomials of degree r over GF(2) can be performed in time $M(r) = O(r \log r \log \log r)$. We have implemented an algorithm of Schönhage [17] that achieves this bound. The algorithm uses a radix-3 FFT and is different from the better-known Schönhage-Strassen algorithm [18]. We remark that the $\log \log r$ term in the time-bound for the Schönhage-Strassen algorithm has been reduced by Fürer [9], but it is not clear if a similar idea can be used to improve Schönhage's algorithm [17]. In any event the $\log \log r$ term comes from the number of levels of recursion and is a small constant for the values of r that we are considering.

In practice, Schönhage's algorithm is not the fastest unless r is quite large. We have also implemented classical, Karatsuba and Toom-Cook algorithms that have $M(r) = O(r^{\alpha})$, $1 < \alpha \le 2$, since these algorithms are easier to implement and are faster for small r. Our implementations of the Toom-Cook algorithms TC3 and TC4 are based on recent ideas of Bodrato [1].

For brevity we assume that r is large and Schönhage's algorithm is used. On a 64-bit machine the crossover versus TC4 occurs around degree r = 180000, see [4].

In the complexity estimates we assume that M(r) is a sufficiently smooth and well-behaved function.

By squaring we mean squaring a polynomial of degree < r and reduction mod P(x). Squaring in GF(2)[x]/P(x) can be performed in time $S(r) = \Theta(r) \ll M(r)$ (assuming, as usual, that P(x) is a trinomial). Our algorithm takes advantage of the fact that squaring is much faster than multiplication.

Where possible we use the memory-efficient squaring algorithm of Brent, Larvala and Zimmermann [5], which in our implementation is about 2.2 times faster than the naive squaring algorithm.

2.2. Complexity of GCD. For GCDs we use a sub-quadratic algorithm that runs in time $G(r) = \Theta(M(r) \log r)$. More precisely,

(2.1)
$$G(2r) = 2G(r) + \Theta(M(r)),$$

so

$$M(r) = \Theta(r \log r \log \log r) \Rightarrow G(r) = \Theta(M(r) \log r).$$

If the classical or Karatsuba algorithm (or one of the Toom-Cook class of algorithms) is used for multiplication, then $M(r) = \Theta(r^{\alpha})$ for some $\alpha > 1$, and in this case it follows from (2.1) that

$$G(r) = \Theta(M(r)).$$

In practice, for $r \approx 2.4 \times 10^7$ and our implementation on a 2.2 Ghz Opteron, $S(r) \approx 0.005$ second, $M(r) \approx 2$ seconds, $G(r) \approx 80$ seconds, so $M(r)/S(r) \approx 400$, and $G(r)/M(r) \approx 40$.

2.3. Avoiding GCD computations. In the context of integer factorization, Pollard [16] suggested a blocking strategy to avoid most GCD computations and thus reduce the amortized cost; von zur Gathen and Shoup [12] applied the same idea to polynomial factorization.

The idea of blocking is to choose a parameter $\ell > 0$ and, instead of computing

$$GCD(x^{2^d} + x, P(x))$$
 for $d \in [d', d' + \ell)$,

compute

$$GCD(p_{\ell}(x^{2^{d'}}, x), P(x)),$$

where the interval polynomial $p_{\ell}(X, x)$ is defined by

$$p_{\ell}(X,x) = \prod_{j=0}^{\ell-1} (X^{2^j} + x).$$

In this way we replace ℓ GCDs by one GCD and $\ell-1$ multiplications mod P(x).

The drawback of blocking is that we may have to backtrack if P(x) has more than one factor with degree in the interval $[d', d' + \ell)$, since the algorithm produces the product of these factors. Thus ℓ should not be too large. The optimal strategy depends on the expected size distribution of factors and the ratio of times for GCDs and multiplications.

2.4. Multi-level blocking. Our new idea is to use a finer level of blocking to replace most multiplications by squarings, which speeds up the computation in GF(2)[x]/P(x) of the above interval polynomials. The idea is to split the interval $[d', d' + \ell)$ into $k \ge 2$ smaller intervals of length m over which

(2.2)
$$p_m(X,x) = \prod_{j=0}^{m-1} (X^{2^j} + x) = \sum_{j=0}^m x^{m-j} s_{j,m}(X),$$

where

(2.3)
$$s_{j,m}(X) = \sum_{0 \le k < 2^m, \ w(k) = j} X^k,$$

and w(k) denotes the *Hamming weight* of k, that is the number of nonzero bits in the binary representation of k.

For example, if m = 3, we have:

$$p_m(X,x) = x^3 + x^2(X^4 + X^2 + X) + x(X^6 + X^5 + X^3) + X^7;$$

hence $s_{0,3}(X)=1$, $s_{1,3}(X)=X^4+X^2+X$, $s_{2,3}(X)=X^6+X^5+X^3$, and $s_{3,3}(X)=X^7$.

Note that

$$s_{j,m}(X^2) = s_{j,m}(X)^2$$
 in $GF(2)[x]/P(x)$.

Thus, $p_m(x^{2^d}, x)$ can be computed with cost $m^2S(r)$ if we already know $s_{j,m}(x^{2^{d-m}})$ for $0 < j \le m$. (The constant polynomial $s_{0,m}(X) = 1$ is computed only once.)

Continuing the example with m=3, and assuming that we know $s_{1,3}(x^{2^{d-3}})$, $s_{2,3}(x^{2^{d-3}})$, and $s_{3,3}(x^{2^{d-3}})$, squaring each of these m=3 times gives $s_{1,3}(x^{2^d})$, $s_{2,3}(x^{2^d})$, and $s_{3,3}(x^{2^d})$, from which we can easily get $p_3(x^{2^d},x)$ using the sum in Eq. (2.2).

In this way we replace m-1 multiplications and m squarings — if we used the product in Eq. (2.2) — by m^2 squarings. Each $s_{j,m}$, $0 < j \le m$, requires m squarings to be shifted from argument $x^{2^{d-m}}$ to argument x^{2^d} . The summation in Eq. (2.2) costs only O(mr), which is negligible. Choosing $m \approx \sqrt{M(r)/S(r)}$ (about 20 if $M(r)/S(r) \approx 400$), the speedup over single-level blocking is about $m/2 \approx 10$ (not counting the cost of GCDs).

Von zur Gathen and Gerhard [11, p. 1685] suggested using the same idea with m=2 (thus reducing the number of multiplications by a factor of two), but did not consider choosing an optimal m>2.

At first sight initialization of the polynomials $s_{j,m}(X)$ for X = x might appear to be expensive, since the definition (2.3) involves $O(2^m)$ terms. However, the polynomials $s_{j,m}(X)$ satisfy a "Pascal triangle" recurrence relation

$$s_{j,m}(X) = s_{j,m-1}(X^2) + X s_{j-1,m-1}(X^2)$$

with boundary conditions

$$s_{j,m}(X) = \begin{cases} 0 & \text{if } j > m \ge 0, \\ 1 & \text{if } m \ge j = 0. \end{cases}$$

Using this recurrence, it is easy to compute $s_{j,m}(x) \mod P(x)$ for $0 \le j \le m$ in time $O(m^2r)$. Thus, the initialization is cheap.

To summarise, we use two levels of blocking:

- (1) The outer level replaces most GCDs by multiplications.
- (2) The inner level replaces most multiplications by squarings.
- (3) The parameter $m \approx \sqrt{M(r)/S(r)}$ is used for the inner level of blocking.
- (4) A different parameter $\ell = km$ is used for the outer level of blocking.

For example, suppose S=1/400, M=1, G=40 (where we have normalised so M=1). We could choose $\ell=80$ and m=20. With no blocking, the cost for an interval of length 80 is 80G+80S=3200.2; with 1-level blocking the cost is G+79M+80S=119.2; with 2-level blocking the cost is G+3M+1600S=47.0.

2.5. Sieving out small factors. We define a *small* factor to be one with degree $d < \frac{1}{2} \log_2 r$, so $2^d < \sqrt{r}$. The constant $\frac{1}{2}$ in the definition is arbitrary and could be replaced by any fixed constant in (0,1). A *large* factor is a factor that is not small.

It would be inefficient to find small factors in the same way as large factors. Instead, let $D = 2^d - 1$, $r' = r \mod D$, $s' = s \mod D$. Then

$$P(x) = x^{r} + x^{s} + 1 = x^{r'} + x^{s'} + 1 \mod (x^{D} - 1),$$

so we only need compute

$$GCD(x^{r'} + x^{s'} + 1, x^D - 1).$$

Because $r', s' < D < \sqrt{r}$, the cost of finding small factors is negligible (both theoretically and in practice), so can be neglected.

2.6. Outer-level blocking strategy. The blocksize in the outer level of blocking is $\ell = km$. We take a linearly increasing sequence of block sizes

$$k = k_0 j$$
 for $j = 1, 2, 3, \dots$

where the first interval starts at about $\log r$ (since small factors will have been found by sieving).

The choice $k=k_0j$ leads to a quadratic polynomial for the interval bounds. More generally, we could take k to be a polynomial of degree $\delta>0$ in j, so the interval bounds would be a polynomial of degree $\delta+1$. The analysis of §4 would go through with minor changes. Generally, increasing δ reduces the number of GCDs but increases the number of squarings/multiplications. In practice, we found that the simple choice $\delta=1$ is close to optimal.

In principle, using the data that we have obtained on the distribution of degrees of smallest factors of trinomials (see §3), and assuming that this distribution is not very sensitive to the degree r, we could obtain a strategy that is close to optimal. However, the choice k_0j with suitable k_0 is easy to implement and not too far from optimal. The number of GCD and sqr/mul operations is usually within a factor of 1.5 of the minimum possible in our experiments.

3. Distribution of degrees of factors

In order to predict the expected behaviour of our algorithm, we need to know the expected distribution of degrees of smallest irreducible factors. From Swan's theorem [22], we know that there are significant differences between the distribution of factors of trinomials and of all polynomials of the same degree. Our complexity estimates are based on the heuristic assumption that this difference is not too large, in a sense made precise by Hypothesis 3.1.

HYPOTHESIS 3.1. Over all trinomials $x^r + x^s + 1$ of degree r over GF(2), the probability π_d that a trinomial has no nontrivial factor of degree $\leq d$, $1 < d \leq r$, is at most c/d, where c is a constant.

Hypothesis 3.1 implies that there are at most c irreducible trinomials of degree r. This is probably false, as there may well be a sequence of exceptional r for which the number of irreducible trinomials is unbounded. Thus, we may need to replace the constant c in Hypothesis 3.1 by a slowly-growing function c(r). Nevertheless, in order to give realistic complexity estimates that are in agreement with experiments, we assume below that Hypothesis 3.1 is correct. Under this assumption we use an amortized model to obtain the total complexity over all trinomials of degree r.

From Hypothesis 3.1, the probability that a trinomial does not have a small factor (as defined in §2.5) is $O(1/\log r)$.

Table 1 gives the observed values of $d\pi_d$ for r=3021377, r=6972593, and r=24036583. The maximum values for each r are given in bold. The table shows that the values of $d\pi_d$ are remarkably stable for small d, and bounded by 4 for large d (this is because there are four irreducible trinomials of degree 3021377 and also four of degree 24036583, when we count both trinomials $x^r + x^s + 1$ and their reciprocals $x^r + x^{r-s} + 1$).

d	r = 3021377	r = 6972593	r = 24036583
2	1.333	1.333	1.333
3	1.429	1.429	1.429
4	1.524	1.524	1.524
5	1.536	1.536	1.536
6	1.598	1.598	1.598
7	1.600	1.600	1.600
8	1.667	1.667	1.667
9	1.642	1.642	1.642
10	1.652	1.652	1.652
100	1.763	1.771	1.770
1000	1.783	1.756	1.786
10000	1.946	1.873	1.786
100000	1.986	1.606	1.880
279383	1.480	2.084	1.813
1000000	1.324	1.147	1.831
10000000	_	_	1.664
r-1	4.000	2.000	4.000

Table 1. $d\pi_d$ for various degrees r.

3.1. Consequences of the hypothesis. Define $p_k = \pi_{d-1} - \pi_d$ to be the probability that the smallest nontrivial factor f of a randomly chosen trinomial has degree $d = \deg(f)$. In order to estimate the running time of our algorithm, we use the following Lemma, which gives the expectation E_{β} of d^{β} .

LEMMA 3.2. If $\beta > 0$ is constant and Hypothesis 3.1 holds, then

$$E_{\beta} := \sum_{d=1}^{r} d^{\beta} p_{d} = \begin{cases} O(1) & \text{if } \beta < 1, \\ O(\log r) & \text{if } \beta = 1, \\ O(r^{\beta - 1}) & \text{if } \beta > 1. \end{cases}$$

PROOF. We use summation by parts. Note that a trinomial has no factor of degree 1, so $p_1 = 0$ and $\pi_0 = \pi_1 = 1$. Thus

$$E_{\beta} = \sum_{d=1}^{r} d^{\beta} p_{d} = \sum_{d=1}^{r} d^{\beta} (\pi_{d-1} - \pi_{d})$$

$$= \sum_{d=1}^{r-1} ((d+1)^{\beta} - d^{\beta}) \pi_{d} + \pi_{0} - r^{\beta} \pi_{r}$$

$$\leq 1 + c \sum_{d=1}^{r-1} \frac{(d+1)^{\beta} - d^{\beta}}{d} \text{ (by Hypothesis 3.1)}$$

$$\leq 1 + O\left(\sum_{d=1}^{r-1} d^{\beta-2}\right)$$

and the result follows.

The following Lemma gives a stronger result in the case $\beta < 1$.

Lemma 3.3. If $0 < \beta < 1$, $0 < D \le r$, and Hypothesis 3.1 holds, then

$$\sum_{d=D}^{r} d^{\beta} p_d = O\left(D^{\beta-1}\right).$$

Proof. The proof is similar to that of Lemma 3.2. We end with the upper bound

$$\sum_{d=D}^{r-1} \frac{(d+1)^{\beta} - d^{\beta}}{d} + D^{\beta} \pi_{D-1}.$$

From Hypothesis 3.1, $\pi_{D-1} = O(1/D)$, and the sum over d is $O(D^{\beta-1})$, so the result follows.

4. Expected cost of sqr/mul and GCD

Recall that the inner level of blocking replaces m-1 multiplications by m^2-m squarings, where the choice $m \approx \sqrt{M(r)/S(r)}$ makes the total cost of squarings about equal to the cost of multiplications.

For a smallest factor of degree d, the number of squarings is $m(d + O(\sqrt{d}))$, where the $O(\sqrt{d})$ term follows from our choice of outer-level blocksizes (see §2.6). Averaging over all trinomials of degree r, the expected number of squarings is

$$O\left(m\sum_{d\leq r/2}(d+O(\sqrt{d}))p_d\right),$$

and from Lemma 3.2 this is $O(m \log r)$. Thus, the expected cost of sqr/mul operations per trinomial is

$$O\left(S(r)\log r\sqrt{M(r)/S(r)}\right) = O\left(\log r\sqrt{M(r)S(r)}\right)$$

$$= O\left(r(\log r)^{3/2}(\log\log r)^{1/2}\right).$$
(4.1)

If we used only a single level of blocking, then the cost of multiplications would dominate that of squarings, with an expected cost per trinomial of $O(\log rM(r)) = O(r(\log r)^2 \log \log r)$.

The bound (4.1) is correct as $r \to \infty$. In practice, for $r < 6.4 \times 10^7$, our implementation of Schönhage's FFT-based polynomial multiplication algorithm [17] calls a different multiplication routine (usually TC4) to perform smaller multiplications, rather than recursively calling itself. TC4 has exponent $\alpha' = \ln(7)/\ln(4) \approx 1.4$, so the effective exponent for FFT multiplication is $\alpha = (1 + \alpha')/2 \approx 1.2 > 1$. In this case, the expected cost of sqr/mul operations per trinomial is

(4.2)
$$O\left(\log r\sqrt{M(r)S(r)}\right) = O(r^{(1+\alpha)/2}\log r) = O(r^{1.1\cdots}\log r).$$

4.1. Expected cost of GCDs. Suppose that P(x) has a smallest factor of degree d. The number of GCDs required to find the factor, using our (quadratic polynomial) blocking strategy, is at least 1, and $O(\sqrt{d})$ if d is large. By Hypothesis 3.1, the expected number of GCDs for a trinomial with no small factor is

$$1 + O\left(\sum_{\log_2 r < 2d \le r} d^{1/2} p_d\right),\,$$

and by Lemma 3.3 this is

$$1 + O\left(\frac{1}{\sqrt{\log r}}\right)$$
.

Thus the expected cost of GCDs per trinomial is

$$(4.3) O(G(r)/\log r) = O(M(r)) = O(r\log r\log\log r).$$

The estimate (4.3) is asymptotically less than the expected cost (4.1) of sqr/mul operations. However, if $M(r) = O(r^{\alpha})$ with $\alpha > 1$, then the expected cost of GCDs is $O(r^{\alpha}/\log r)$, which is asymptotically greater than the expected cost (4.2) of sqr/mul operations. Note the expected cost of GCDs does not depend on whether we use one or two levels of blocking.

For $r \approx 2.4 \times 10^7$, GCDs take about 65% of the time versus 35% for sqr/mul.

4.2. Comparison with previous algorithms. For simplicity we use the \widetilde{O} notation which ignores log factors. For example, $M(r) = \widetilde{O}(r)$.

The "naive" algorithm, as implemented by Brent, Larvala and Zimmermann [5] and earlier authors, takes an expected time $\widetilde{O}(r^2)$ per trinomial, or $\widetilde{O}(r^3)$ to cover all trinomials of degree r.

The single-level blocking strategy and the new algorithm both take expected time $\widetilde{O}(r)$ per trinomial, or $\widetilde{O}(r^2)$ to cover all trinomials of degree r.

In practice, the new algorithm is faster than the naive algorithm by a factor of about 160 for r = 6972593, and by a factor of about 560 for r = 24036583. For r = 24036583, where sqr/mul operations take 35% of the total time in the new algorithm, and the corresponding speedup is about 10, this gives a global speedup of more than 4 over the single-blocking strategy.

4.3. Some details of our implementation. We first implemented the 2-level blocking strategy in NTL [19]. To get full efficiency, we rewrote all critical routines and tuned them efficiently on the target processors. Our squaring routine implements the algorithm described in [5], which is more than twice as fast as the corresponding optimized NTL routine for trinomials. Our multiplication routine implements Toom-Cook 3-way, 4-way, and Schönhage's algorithm [17]. We also

improved the basecase multiplication code; more details concerning efficient multiplication in GF(2)[x] are available in [4]. Finally, we implemented a subquadratic GCD routine, since NTL only provides a classical GCD for binary polynomials.

4.4. Primitive trinomials. The largest published primitive trinomial is

$$x^{6972593} + x^{3037958} + 1,$$

found by Brent, Larvala and Zimmermann [5] in 2002 using a naive (but efficiently implemented) algorithm.

In March–April 2007, we tested our new program by verifying the published results on primitive trinomials for Mersenne exponents $r \leq 6972593$, and in the process produced certificates of reducibility (lists of smallest factors for each reducible trinomial). These are available from the first author's website [3].

In April–August 2007, we ran our new algorithm to search for primitive trinomials of degree r=24036583. This is the next Mersenne exponent, apart from two that are trivial to exclude by Swan's theorem. It would take about 41 times as long as for r=6972593 by the naive algorithm, but our new program is 560 times faster than the naive algorithm. Each trinomial takes on average about 16 seconds on a 2.2 Ghz Opteron.

The complete computation was performed in four months, using about 24 Opteron and Core 2 processors located at ANU and INRIA.

We found two new primitive trinomials of (equal) record degree:

$$(4.4) x^{24036583} + x^{8412642} + 1$$

and

$$(4.5) x^{24036583} + x^{8785528} + 1.$$

4.5. Verification. Allan Steel [20] kindly verified irreducibility of (4.4)–(4.5) using Magma [2]. Each verification took about 67 hours on an 2.4 GHz Core 2 processor. Independent verifications using our irred V3.15 program [5, 6] took about 35 hours on a 2.2 Ghz Opteron. The difference in speed is mainly due to the fast squaring algorithm implemented in irred.

Primitivity of (4.4)–(4.5) follows from irreducibility provided that the degree 24036583 is a Mersenne exponent. We have not verified this, but rely on computations performed by the GIMPS project [23].

Reducibility of the remaining trinomials of degree 24036583 can be verified using the certificate (or *extended log*, a list of smallest irreducible factors) available from our website [3]. The verification takes less than 10 hours using Magma on a 2.66 Ghz Core 2 processor.

5. Conclusion

The new double-blocking strategy, combined with fast multiplication and GCD algorithms, has allowed us to find new primitive trinomials of record degree.

The same ideas should work over finite fields GF(p) for small prime p > 2, and for factoring sparse polynomials P(x) that are not necessarily trinomials: all we need is that the time for p-th powers (mod P(x)) is much less than the time for multiplication (mod P(x)).

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