

Comments on non-isometric T-duality

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Based on [\[1705.09254\]](#)
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June 2017

Outline

- 1 Isometric T-duality
- 2 Non-isometric T-duality
- 3 Equivalence
- 4 Examples

Setting up notation

Consider a non-linear sigma model $X : \Sigma \rightarrow M$ described by the following action:

$$S = \int_{\Sigma} g_{ij} dX^i \wedge \star dX^j + \int_{\Sigma} B_{ij} dX^i \wedge dX^j$$

In this talk we will ignore the dilaton, and assume that both g and B are globally defined fields on M .

Gauging isometries

Suppose now that there are vector fields generating the following global symmetry:

$$\delta_\epsilon X^i = v_a^i \epsilon^a$$

for ϵ^a constant. The sigma model action is invariant under this transformation if

$$\mathcal{L}_{v_a} g = 0 \quad \mathcal{L}_{v_a} B = 0$$

If this is the case, we can gauge the model by promoting the global symmetry to a local one.

The gauged action

Introducing gauge fields A^a and Lagrange multipliers η_a , the gauged action is

$$S_G = \int_{\Sigma} g_{ij} DX^i \wedge \star DX^j + \int_{\Sigma} B_{ij} DX^i \wedge DX^j + \int_{\Sigma} \eta_a F^a$$

where

- $F = dA + A \wedge A$ is the standard Yang-Mills field strength
- $DX^i = dX^i - v_a^i A^a$ are the gauge covariant derivatives.

Gauge invariance

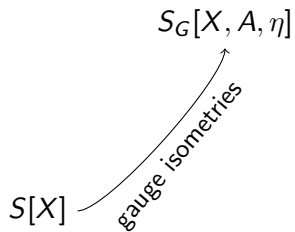
The gauged action is invariant with respect to the following (local) gauge transformations:

$$\delta_\epsilon X^i = v_a^i \epsilon^a$$

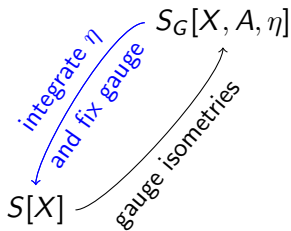
$$\delta_\epsilon A^a = d\epsilon^a + C_{bc}^a A^b \epsilon^c$$

$$\delta_\epsilon \eta_a = -C_{ab}^c \epsilon^b \eta_c$$

T-duality

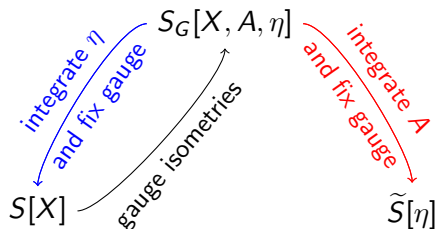


T-duality



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On the other hand, we can eliminate the non-dynamical gauge fields A , obtaining the dual sigma model.

Can we do it without isometries?

The existence of global symmetries is a very stringent requirement. A generic metric will not have any Killing vectors.

Question

Is it possible to follow the same procedure when the vector fields are not Killing vectors?

Gauging without isometry

Kotov and Strobl¹ introduced a method of gauging a sigma model without requiring the model to possess isometries.

Their method uses Lie algebroids, and generalises the standard gauging in two notable ways:

- The structure constants of the Lie algebra are promoted to structure functions:

$$[v_a, v_b] = C_{ab}^c(X) v_c$$

- The gauge invariance of the gauged action doesn't require the original vector fields to be isometries:

$$\mathcal{L}_{v_a} g \neq 0 \quad \mathcal{L}_{v_a} B \neq 0$$

¹[\[1403.8119\]](#)

Non-isometric T-duality

Chatzistavrakidis, Deser, and Jonke² applied this non-isometric gauging to the Buscher procedure we just reviewed.

They promote the structure constants to functions, and introduce a matrix-valued one-form ω_a^b satisfying

$$\begin{aligned}\mathcal{L}_{v_a} g &= \omega_a^b \vee \iota_{v_b} g \\ \mathcal{L}_{v_a} B &= \omega_a^b \wedge \iota_{v_b} B\end{aligned}$$

²[\[1509.01829\]](#) and [\[1604.03739\]](#)

The gauged action

The gauged action is almost the same:

$$S_G^\omega = \int_\Sigma g_{ij} DX^i \wedge \star DX^j + \int_\Sigma B_{ij} DX^i \wedge DX^j + \int_\Sigma \eta_a F_\omega^a$$

where the curvature is now given by

$$F_\omega^a = dA^a + \frac{1}{2} C_{bc}^a(X) A^b \wedge A^c - \omega_{bi}^a A^b \wedge DX^i$$

Modified gauge invariance

The modified gauge transformations are now

$$\delta_\epsilon X^i = v_a^i \epsilon^a$$

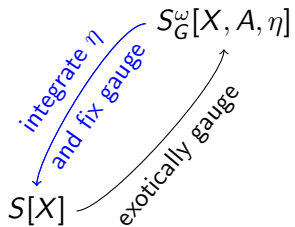
$$\delta_\epsilon A^a = d\epsilon^a + C_{bc}^a A^b \epsilon^c + \omega_{bi}^a \epsilon^b DX^i$$

$$\delta_\epsilon \eta_a = -C_{ab}^c \epsilon^b \eta_c + v_a^i \omega_{bi}^c \epsilon^b \eta_c$$

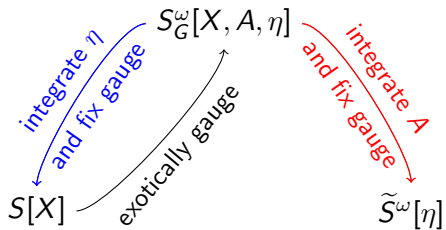
T-duality

$$S[X] \xrightarrow{\text{exotically gauge}} S_G^\omega[X, A, \eta]$$

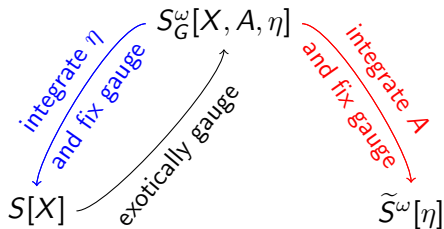
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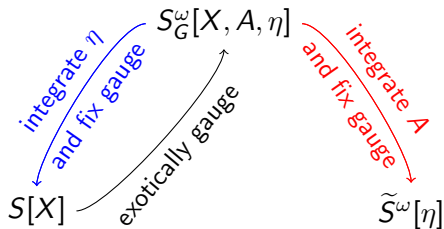


T-duality



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In principle, we could use this to construct T-duals of spaces which have no isometries.

The problem?

This proposal is equivalent to non-abelian T-duality.³

That is, if we can find a set of vector fields and ω_a^b which give a non-isometric T-dual, then there exists a set of Killing vectors for the model. The T-dual with respect to these Killing vectors is the same as the non-isometric T-dual.

³[\[1705:09254\]](#) P. Bouwknegt, M.B., C. Klimčík, K. Wright

A necessary condition for gauge invariance

Gauge invariance of the action requires the structure functions to be constant, as well as the vanishing of the following variation:

$$\delta_\epsilon(\eta_a F_\omega^a) = \eta_a (d\omega_b^a + \omega_c^a \wedge \omega_b^c) \epsilon^b + \mathcal{O}(A) + \mathcal{O}(A^2).$$

We therefore require that ω_a^b is flat:

$$R_a^b = d\omega_a^b + \omega_c^b \wedge \omega_a^c = 0,$$

and this tells us that ω_a^b is of the form $K^{-1}dK$ for some $K_a^b(X)$.

A field redefinition

Using this K , we can perform the following field redefinitions:

$$\widehat{A}^a = K_b^a A^b$$

$$\widehat{\eta}^a = \eta_b (K^{-1})_a^b$$

$$\widehat{v}_a = v_b^i (K^{-1})_a^b$$

The non-abelian action!

The gauged action can now be rewritten in terms of the new fields $(X^i, \widehat{A}^a, \widehat{\eta}_a)$.

$$\begin{aligned} S_G^\omega[X, \widehat{A}, \widehat{\eta}] &= \int_\Sigma g_{ij} \widehat{DX}^i \wedge \star \widehat{DX}^j + \int_\Sigma B_{ij} \widehat{DX}^i \wedge \widehat{DX}^j + \int_\Sigma \widehat{\eta}_a \widehat{F}^a \\ &= S_G[X, \widehat{A}, \widehat{\eta}] \end{aligned}$$

where

$$\widehat{F}^a = d\widehat{A}^a + \frac{1}{2} \widehat{C}_{bc}^a \widehat{A}^b \wedge \widehat{A}^c$$

The gauge transformations become the usual non-abelian gauge transformations, and a short computation reveals

$$\mathcal{L}_{\widehat{v}_a} g = 0 \quad \mathcal{L}_{\widehat{v}_a} B = 0$$

Conclusion

This proposal is equivalent, via a field redefinition, to the standard non-abelian T-duality

First example

Consider the 3D Heisenberg Nilmanifold, or twisted torus. It has a metric given by

$$ds^2 = dx^2 + (dy - x dz)^2 + dz^2$$



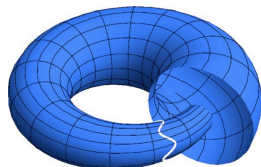
The non-abelian T-dual of this space is given by

$$\widehat{ds}^2 = dY^2 + \frac{1}{1 + Y^2} (dX^2 + dZ^2)$$
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First example

We can gain a better understanding of the geometry by writing the manifold as a group:

$$\text{Heis} := \left\{ \begin{pmatrix} 1 & x & y \\ 0 & 1 & z \\ 0 & 0 & 1 \end{pmatrix} : x, y, z \in \mathbb{R} \right\}$$

(left-invariant) MC forms = $(dx, dy - xdz, dz)$

(right-invariant) vector fields = $(\partial_x + z\partial_y, \partial_y, \partial_z)$

First example

We could instead try to gauge this space non-isometrically using the left-invariant vector fields: $\{\partial_x, \partial_y, x\partial_y + \partial_z\}$.

These are not all isometries:

$$\mathcal{L}_{v_1}g = -dy \otimes dx - dz \otimes dy + 2xdz \otimes dz$$

$$\mathcal{L}_{v_2}g = 0$$

$$\mathcal{L}_{v_3}g = dx \otimes dy + dy \otimes dx - xdx \otimes dz - xdz \otimes dx$$

and they don't commute:

$$[v_1, v_3] = v_2,$$

however...

First example⁴

If we take $\omega_3^2 = dx$ and $\omega_1^2 = -dz$, with other components vanishing, the non-isometric gauging constraints are satisfied and we can calculate the non-isometric T-dual model.

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⁴Gauged non-isometrically in [\[1509:01829\]](#)

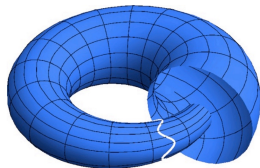
A. Chatzistavrakidis, A. Deser, L. Jonke

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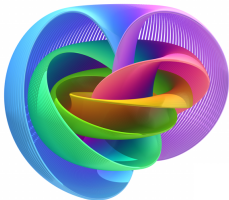
Unsurprisingly, it is also the T-fold.

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Second example

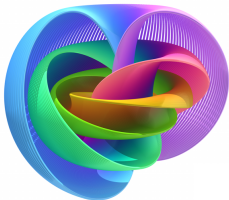
Consider S^3 with the round metric and $B = 0$.



This metric has an $SO(4)$ group of isometries, and we can find the non-abelian T-dual with respect to an $SU(2)$ subgroup of this.

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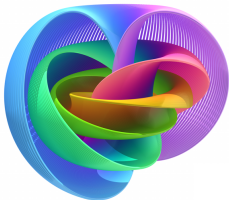


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Second example

We can write the round metric as

$$g = \lambda^1 \otimes \lambda^1 + \lambda^2 \otimes \lambda^2 + \lambda^3 \otimes \lambda^3$$

where the λ^i are the left-invariant Maurer-Cartan forms.

The right-invariant vector fields are isometries of this metric, so let's try gauging with respect to the left-invariant vector fields⁵.

⁵These also happen to be isometries of the metric, but let's try to gauge them non-isometrically

Second example

The Lie derivatives of the metric with respect to the left-invariant vector fields, L_a are

$$\begin{aligned}\mathcal{L}_{L_a}g &= - \sum_b C_{ac}^b \lambda^c \vee \lambda^b \\ &= - C_{ac}^b \lambda^c \vee \iota_{L_b}g\end{aligned}$$

We can do non-isometric T-duality by taking $\omega_a^b = -C_{ac}^b \lambda^c$.

Second example

The remaining gauging constraints are satisfied, and we can calculate the non-isometric T-dual. It is the 'cigar' metric, as expected.



Comments

- The equivalence of non-isometric and non-abelian T-duality remains valid for non-exact H
- Geometric interpretation of ω_a^b as a connection on a Lie algebroid
- There are proposals for alternate gauging. Unknown how to incorporate into T-duality
 - non-flat ω_a^b
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Thanks!