## 2.6. Leave-one-out residuals

This is the element in the (j, j) position of

$$\frac{\mathbf{Q}_r \, \mathbf{Q}_r^{\mathsf{T}} \mathbf{y}}{\alpha} = \frac{\mathbf{I} - \mathbf{Q}_f \, \mathbf{Q}_f^{\mathsf{T}} \mathbf{y}}{\alpha}$$

i.e., it equals  $e_j/\alpha$ , where  $e_j$  is the residual from the model that includes the  $j^{th}$  row. In place of **R** $\beta$  = **f**, the regression parameters are obtained by solving

$$\begin{bmatrix} \mathbf{R} & \mathbf{q}_{j(f)} \\ 0 \dots 0 & \alpha \end{bmatrix} \begin{bmatrix} \tilde{\boldsymbol{\beta}} \\ \boldsymbol{\zeta} \end{bmatrix} = \begin{bmatrix} \mathbf{f} \\ \frac{e_j}{\alpha} \end{bmatrix}$$

Hence

$$e_{(j)} = \frac{e_j}{\alpha^2} \tag{19}$$

$$= \frac{e_j}{\|\mathbf{q}_{j(r)}\|^2}$$
(20)

$$=\frac{e_j}{1-a_{jj}}\tag{21}$$

where  $a_{ij}$  is the  $j^{th}$  diagonal element of the matrix

$$\mathbf{A} = \mathbf{Q}_f \mathbf{Q}_f^{\mathsf{T}} = \mathbf{I} - \mathbf{Q}_r \mathbf{Q}_r^{\mathsf{T}}$$
(22)

Notice that we have not made any assumption of non-singularity.

## 2.6.1. The OCV mean square error

It follows from Equation 21 that the *ordinary cross-validation* (OCV) mean square error statistic:

$$OCV = \frac{1}{n} \sum_{j=1}^{n} e_{(j)}^{2} = \frac{1}{n} \sum_{j=1}^{n} \frac{e_{j}^{2}}{(1 - a_{jj})^{2}}$$
(23)

This is a weighted sum of the squares of the ordinary residuals. High leverage points (large  $1 - a_{ii}$  get the greatest weight.

In Subsection 2.6.2 that now follows, it will be argued that the *generalized cross-validation* (GCV) mean square prediction error estimate is preferable.

## 2.6.2. The GCV statistic

This continues the discussion above. The GCV statistic is based on an orthonormal rotation of the row space of  $\mathbf{X}$ , where the rotation is chosen to yield pseudo-observations that all have equal leverage.

If **P** is any orthonormal matrix

$$\|\mathbf{P}\mathbf{y} - \mathbf{P}\mathbf{X}\boldsymbol{\beta}\|^2 = (\mathbf{y} - \mathbf{X}\boldsymbol{\beta})^\top P^\top P(\mathbf{y} - \mathbf{X}\boldsymbol{\beta})$$
$$= (\mathbf{y} - \mathbf{X}\boldsymbol{\beta})^\top (\mathbf{y} - \mathbf{X}\boldsymbol{\beta})$$
$$= \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|^2$$

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## 2. Solving Least Squares Systems

Thus minimization of  $||\mathbf{y} - \mathbf{X}\boldsymbol{\beta}||^2$  is equivalent to minimization of  $||\mathbf{P}\mathbf{y} - \mathbf{P}\mathbf{X}\boldsymbol{\beta}||^2$ . The effect is to replace columns of **X** by columns of **PX**, and elemement of **y** by elements of **Py**. Where the ordinary least squares residuals were  $\boldsymbol{\epsilon}$  they are now  $\mathbf{P}\boldsymbol{\epsilon}$ . We have created a set of pseudo-observations and pseudo-residuals, iid normal if the elements of  $\boldsymbol{\epsilon}$  are iid normal. If the observations are replaced by these pseudo-observations, the OCV statistic changes.

The GCV statistic is the OCV statistic that results from choosing  $\mathbf{P}$  so that all pseudoobservations have equal leverage. It is not necessary to find such a  $\mathbf{P}$  in order to calculate the GCV statistic; all that is necessary is to show that such a choice is possible.<sup>2</sup>

Now suppose that, as before, premultiplication by  $\mathbf{Q}_f^{\mathsf{T}}$  reduces  $\mathbf{X}$  to upper triangular form. Then

$$\mathbf{Q}_f^{\mathsf{T}} \mathbf{P}^{\mathsf{T}} \mathbf{P} \mathbf{X} = \mathbf{Q}_f^{\mathsf{T}} \mathbf{P}^{\mathsf{T}} (\mathbf{P} \mathbf{X})$$

i.e., premultiplication by  $\mathbf{Q}_f^{\mathsf{T}} \mathbf{P}^{\mathsf{T}}$  reduces **PX** to upper triangular form. The leverages for these pseudo-observations are diagonal elements of

$$\mathbf{P}\mathbf{Q}_{r}\mathbf{Q}_{r}^{\mathsf{T}}\mathbf{P}^{\mathsf{T}}=\mathbf{I}_{n}-\mathbf{P}\mathbf{Q}_{f}\mathbf{Q}_{f}^{\mathsf{T}}\mathbf{P}^{\mathsf{T}}$$

Moreover the sum of the leverages is

trace(
$$\mathbf{P}\mathbf{Q}_{r}\mathbf{Q}_{r}^{\mathsf{T}}\mathbf{P}^{\mathsf{T}}$$
) = trace( $\mathbf{Q}_{r}\mathbf{Q}_{r}^{\mathsf{T}}\mathbf{P}^{\mathsf{T}}\mathbf{P}$ )  
= trace( $\mathbf{Q}_{r}\mathbf{Q}_{r}^{\mathsf{T}}$ )  
= trace( $\mathbf{I} - \mathbf{Q}_{f}\mathbf{Q}_{f}^{\mathsf{T}}$ )  
=  $n - \sum_{i=1}^{n} a_{ii}$ 

The sum of the leverages is  $n - \sum_{i=1}^{n} a_{ii}$ , just as for the unrotated configuration. In the equal leverages configuration, the leverages are thus all equal to

$$\frac{1}{n}\left(n-\sum_{i=1}^{n}a_{ii}\right)$$

The sum of squares of the estimated pseudo-residuals is unchanged. Ordinary cross-validation gives, for these pseudo-observations, the *generalized cross-validation* (GCV) estimate

$$\frac{n\sum_{i=1}^n e_i^2}{(n-\sum_{i=1}^n a_{ii})^2}$$

Not only does this have better theoretical properties than OCV; it is simpler computationally. It is, as for the OLS estimate, derived from the residual sum of squares.

The divisor  $n - \sum_{i=1}^{n} a_{ii}$  has the same role as the degrees of freedom in the classical theory.

<sup>&</sup>lt;sup>2</sup>One way to show this is to note that if two rows have different  $L_2$  norms, then we can find a Givens rotation that equalizes the lengths. This process can be repeated until all rows are, to within numerical error, of equal length.